

Modeling and Simulation of Industrial Control Systems

Ines Ugalde

Advanced Manufacturing Automation

Siemens Corporate Technology USA

Siemens Company Structure (375,000 Employees)



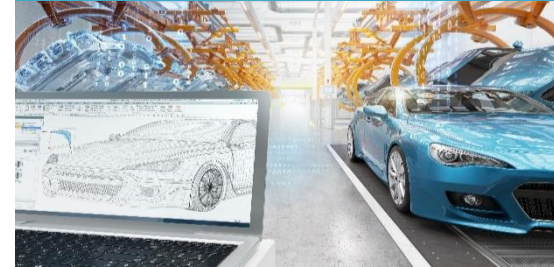
Power and Gas



Building Technologies



Digital Factory



Siemens
Healthineers



Energy Management



Mobility



Processes and Drives



Siemens Gamesa
Renewable Energy



Corporate Technology (7,000 employees, 1,600 researchers)

CT AMA – Advanced Manufacturing Automation

Bridging the Gap between University Research and Industry

Mission: Located in **Berkeley, CA**, we *Scout* and *Evaluate* new automation & control technologies in collaboration with leading academic institutions and government agencies.

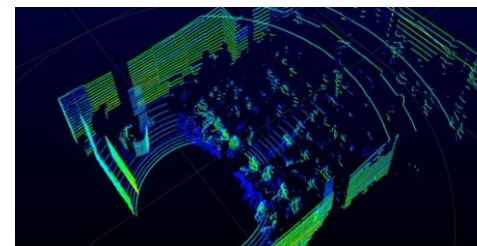
Research Areas

Advanced Robotics

Advanced Control & Optimization

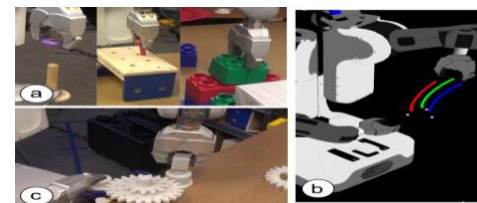
Smart Factories

Examples of University Collaborations



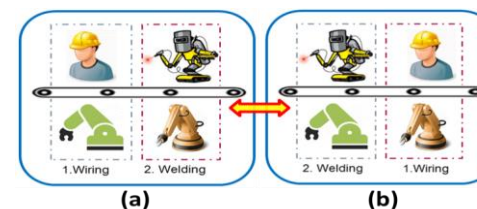
Situation Awareness in a Manufacturing Setting

Univ. Washington



Deep Reinforcement Learning of Robotic Assembly Tasks

UC Berkeley



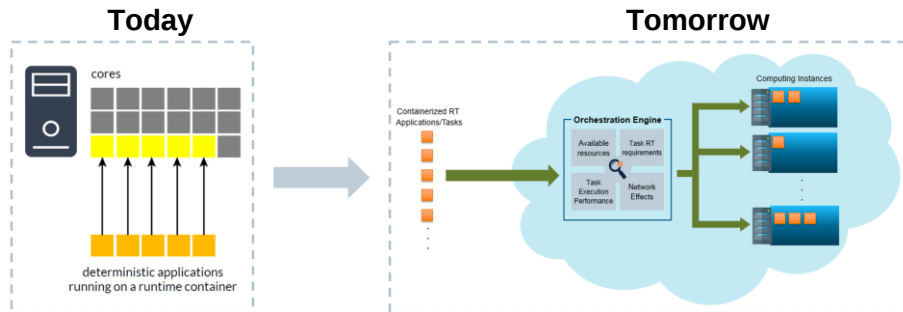
Self-learning Manufacturing Systems

Stanford

Research Collaboration: iCyPhy and Siemens

Siemens is an iCyPhy member since 2017

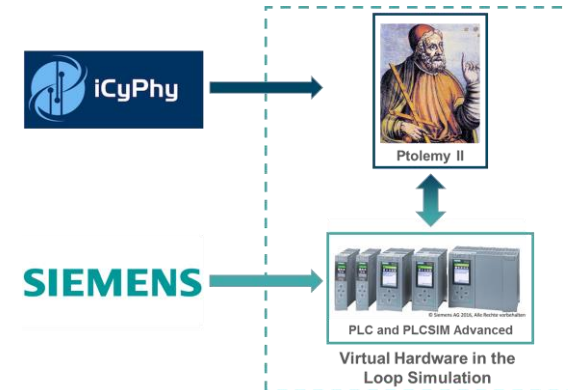
Real-time Virtual Containers for Industrial Control Systems



- **State of the art:** One task per virtual core, No RT guarantees
- **Our approach:**
 - Dynamic Task Scheduler and Monitor
 - Real-time guarantees
 - Optimize virtual core usage (multiple tasks per core)

Prof. Alberto Sangiovanni-Vincentelli

Modeling and Simulation of Industrial Control Systems



Initial Goal:

Leverage Ptolemy II Cyber-Physical System Models in Virtual Hardware in the Loop Simulation with PLCSIM Advanced

New Goal:

Define a PLC Programming Model addressing *deterministic execution*

Prof. Edward A. Lee

Programmable Logic Controllers

Ecosystem for factory and industrial process



Robust,
ruggedized
hardware



Software Logic
and IDE



RT Networks
interconnecting sensors
and actuators

OB

Organization blocks are **preemptable** tasks invoked periodically or at events (*prioritized interrupts*)

FB

Function Block with persistent state, like a C++ object
Can be called from an OB

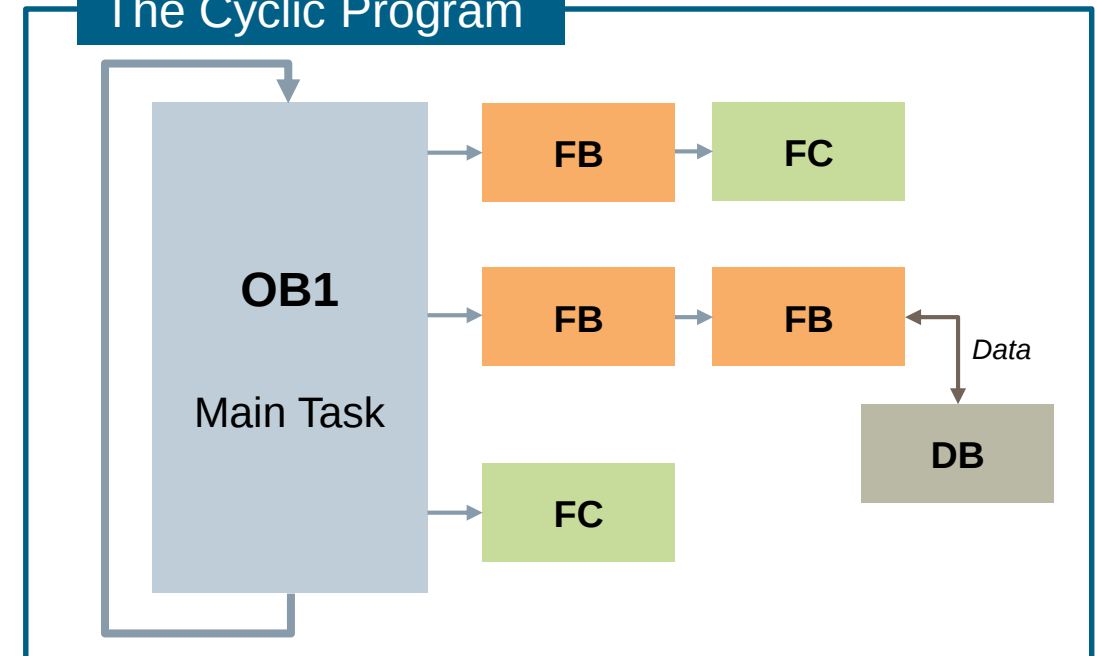
FC

Function without persistent state, like a C function
Can be called from an OB or an FB

DB

Data Blocks store variables
Same DB may be accessed by multiple FBs

The Cyclic Program



Ambiguities in current PLC Programming Scene

- 1. Input signals are updated on a cycle basis of variable duration**
Arrival time of signals in between cycles cannot be distinguished
- 2. Ambiguous use of memory**
Data Blocks may be changed across tasks/FBs within the same cycle
FB execution may not be atomic, its inputs may change during its execution and its outputs may be visible before execution is done
- 3. Timing behaviors are difficult to understand**
Coexisting clocks and synchronization methods on the network make reasoning about system behavior difficult to understand



Research Areas

1. Rely less on cyclic computations
 - Reduce network polling to check if “something has changed”
 - Favor event-based programming models, like PTIDES
2. Software components should specify timing requirements instead of (in addition to) priorities.
Given only priorities, the actual behavior of one component may depend on other (unrelated) components
3. Software behavior should be more independent of hardware
 - Aim for more deterministic software response facilitating the job of Virtual Prototyping
4. Enforce a more disciplined use of memory
 - By means of message-passing communication mechanisms

Ines Ugalde
Research Engineer

Martin Sehr
Research Scientist / R&D Project Manager