Embedded S/W Development Using PTII

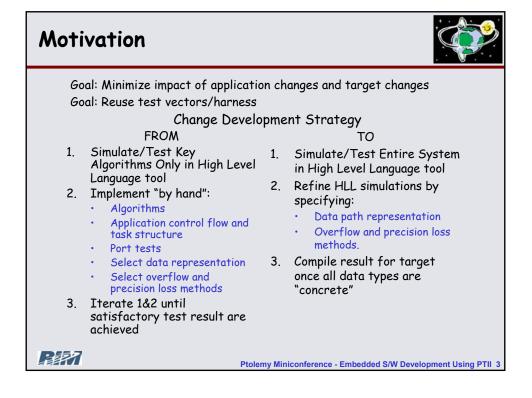
Modeling Extensions, Data Representation, Compilation

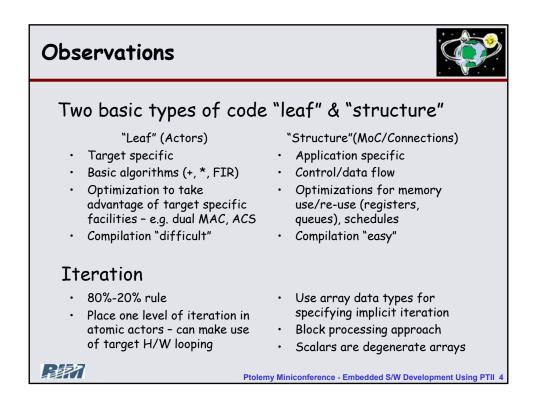
Zoltan Kemenczy, Sean Simmons Research in Motion Limited

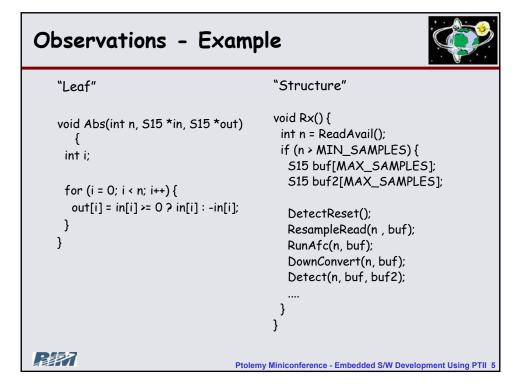
5th Biennial Ptolemy Miniconference Berkeley, CA, May 9, 2003

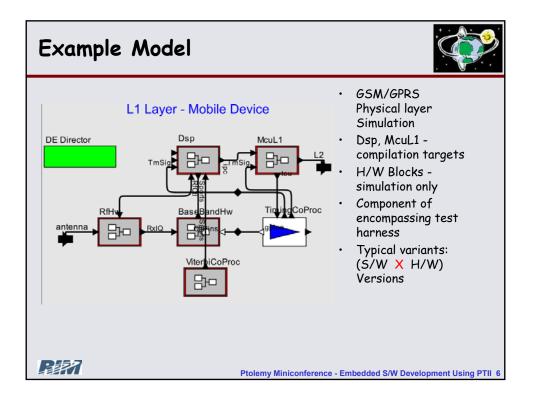


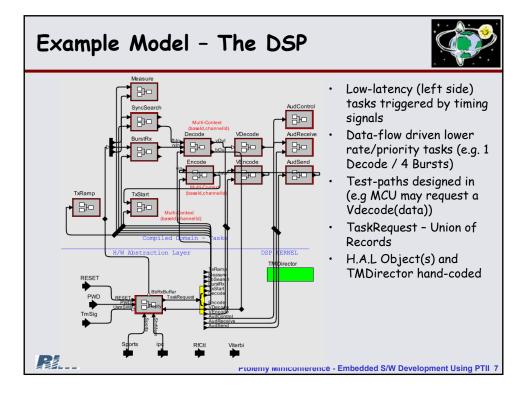
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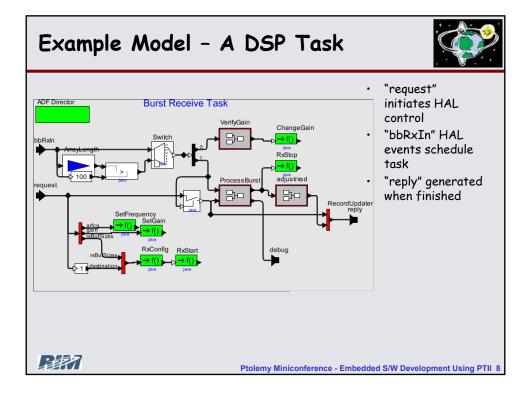












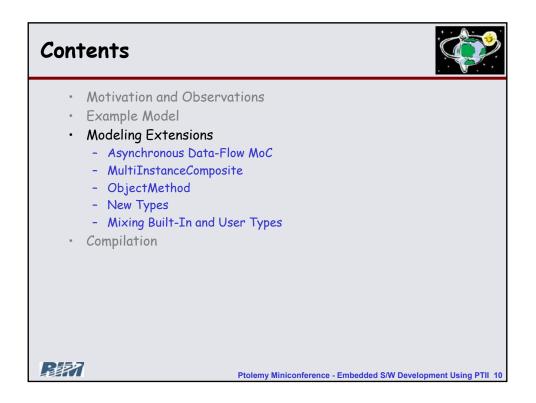


Example - Summary

Component	Simulation	Target	Goals
MCU and DSP	TM, ADF, SDF, FSM	Compiled	•Single model / feature set •Model "run" in different targets (PTII, Target Simulation, Device)
PTII "Library"	n/a	Hand- Coded	•Actors •Schedulers •Type/Token/Port handling
HAL	DE	Hand- Coded	•HAL Minimal but complete •Handle different H/W platforms, versions •Simulation true to HAL API
Timing, Coding, Cipher	DE	H/W	
Radio, Baseband, Comm.	DE	H/W	

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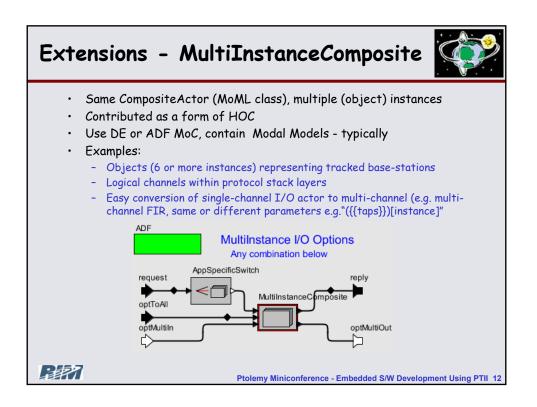
Extensions: Asynchronous Data Flow MoC

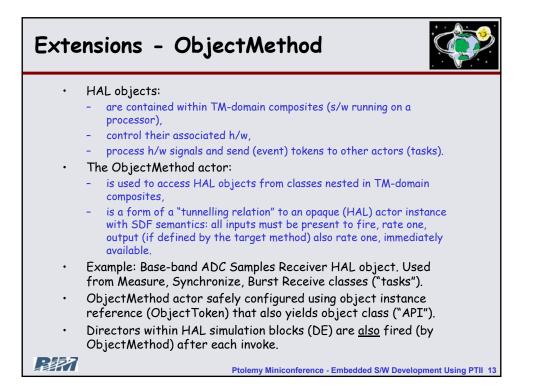


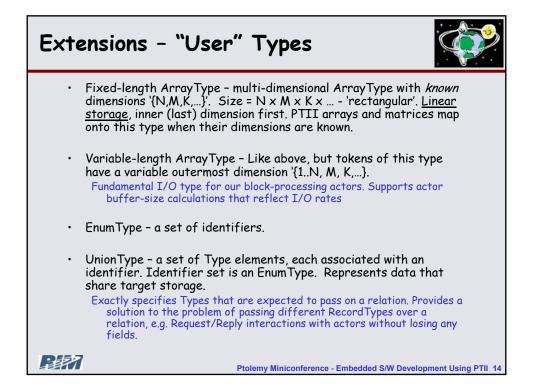
- Data flow driven like SDF
- Dynamic schedule like DE
- No notion of time (local or global) like SDF
 - No global event queue like SDF
 - Local queues on each port
- Loops are allowed
 - Requires use of a "register" actor
 - Same idea as "zero delay" in DE or Z⁻¹ in SDF.
- Port rates computed like SDF
 - Represent maximum number of tokens produced when fired
 - Used to compute queue sizes for compilation
- Uses fixed firing order
 - Uses prefire to evaluate actor's readiness
 - Repeatedly fires actors in sequence until all actors prefire methods returns false

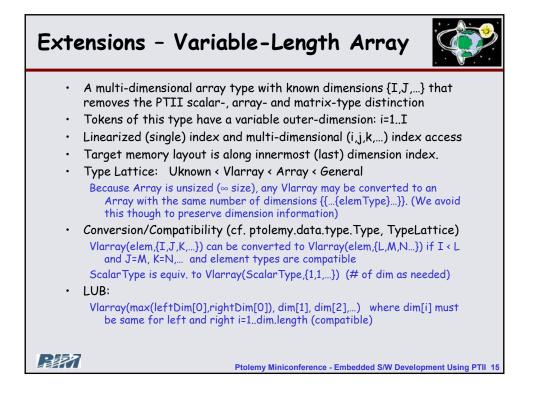
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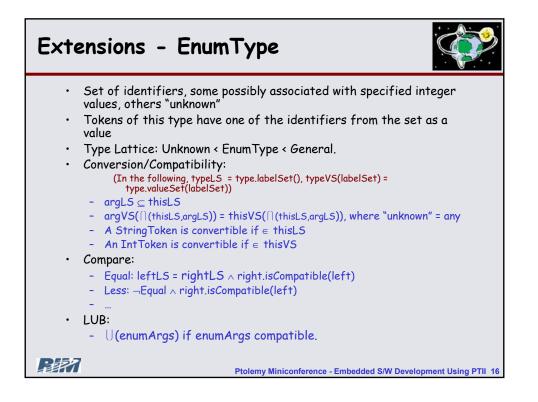
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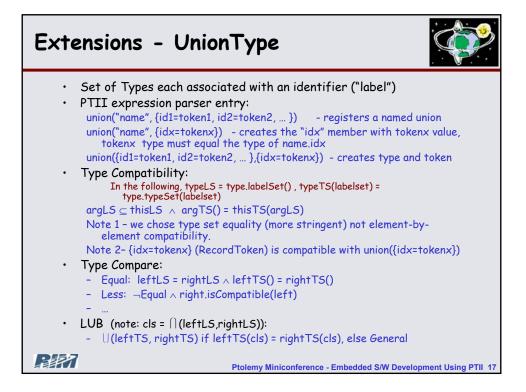


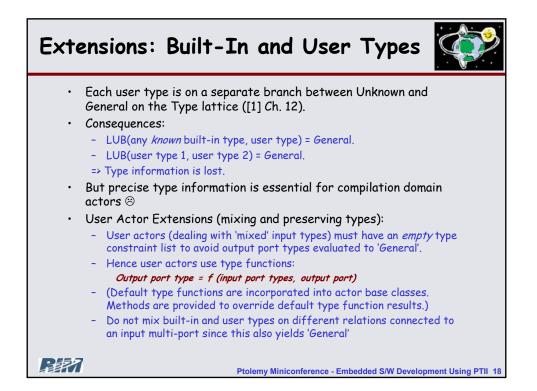


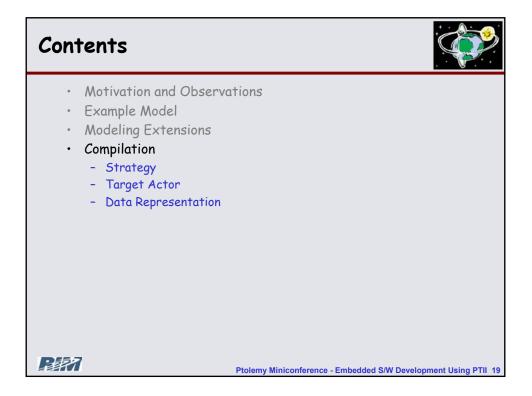


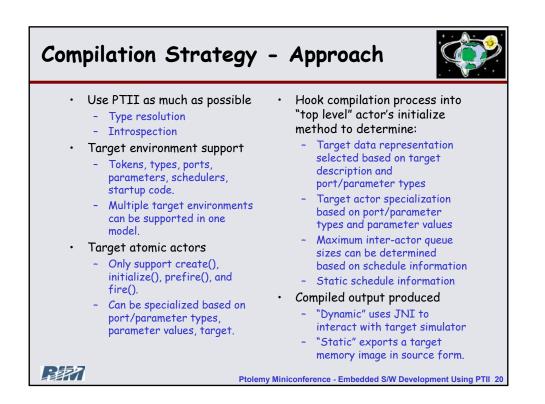


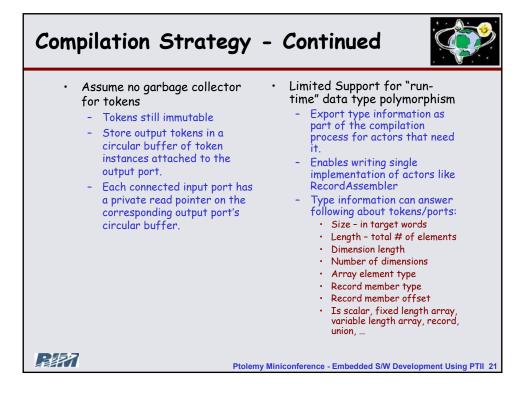


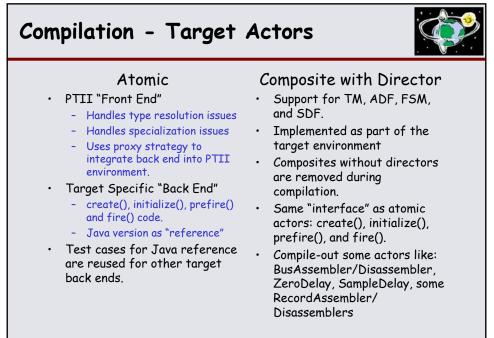














Compilation - Target Actor Tradeoffs



- Granularity of atomic actors
 - Use application to guide development
 - E.g. Butterfly actor vs FFT actor.
- Specialization of atomic actors
 - Development time vs. runtime overhead.
 - Different targets can make different trade-offs
 - E.g. In add actor test overflow mode at runtime or create multiple specializations of add actor, one for each overflow mode. Use of a template strategy can help here.
- Appropriate array dimension handling
 - "Vector actors" "linearize" multi-dimensional arrays.
 Works well for element-by-element operations like add, multiply, etc.
 - Actor loop overheads vs. explicit dimension reduction/aggregation actors (and associated data copying)
 - E.g. Max actor with two dimensional input which is to act over "columns". Can create specialized actor implementation that contains double loop, or can explicitly convert two dimensional input array to a sequence of one dimensional arrays and then collect the scalar results back into a one dimensional output array.

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