

# Dataflow Process Networks

## An Introduction to a Mathematical Model of Dataflow

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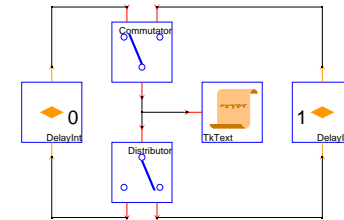
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# 1 Process Networks

Produce a stream of 0's and 1's.  
(from figure 2 in Kahn74)

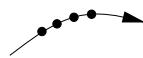


- concurrent processes
- FIFO communication channels, unbounded capacity
- non-blocking writes, blocking reads

## 1.1 Kahn's Formal Model

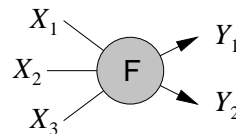
- A stream is a sequence of data tokens:

$$X_1 = [x_1, x_2, x_3, \dots], \perp = \text{empty.}$$



- A process is a functional mapping from one set of sequences into another:

$$F(\vec{X}) = \vec{Y}$$



- blocking reads  $\implies$  determinate system

## 1.2 Streams

Stream:

$$X = [x_1, x_2, \dots] \in S$$

$$\perp = [] \in S$$

$$\vec{X} = \{X_1, X_2, \dots, X_p\} \in S^p$$

$$\vec{\perp} = \{\perp, \perp, \dots, \perp\} \in S^p$$

Prefix Order:

$$[x_1, x_2] \sqsubseteq [x_1, x_2, x_3]$$

$$\vec{X} \sqsubseteq \vec{Y} \iff X_i \sqsubseteq Y_i \quad \forall X_i \in \vec{X}$$

**Increasing Chain:**

$$\mathcal{X} = \{\vec{X}_1, \vec{X}_2, \dots\}$$

$$\vec{X}_1 \sqsubseteq \vec{X}_2 \sqsubseteq \dots$$

**Greatest Lower Bound:**

$$\sqcup \mathcal{X} \sqsubseteq \vec{X}_i \quad \forall \vec{X}_i \in \mathcal{X}$$

**Least Upper Bound:**

$$\vec{X}_i \sqsubseteq \sqcap \mathcal{X} \quad \forall \vec{X}_i \in \mathcal{X}$$

**1.3 Processes****Process:**

$$F : S^p \longrightarrow S^q$$

**Continuous:**

$$F(\sqcap \mathcal{X}) = \sqcap F(\mathcal{X})$$

$$\sqcap F(\mathcal{X}) = \sqcap \{F(\vec{X}_1), F(\vec{X}_2), \dots\}$$

**Monotonic:**

$$\vec{X} \sqsubseteq \vec{Y} \implies F(\vec{X}) \sqsubseteq F(\vec{Y})$$

**Sequential:** F is continuous and

$$\forall \vec{X} \in S^p \quad \exists X_i \in \vec{X}$$

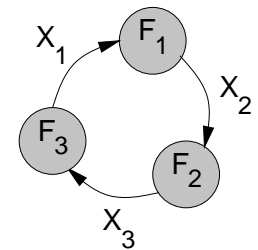
such that

$$F(\vec{X}) = F(\vec{Y})$$

$$\forall \vec{Y}, \quad X_i = Y_i \quad \text{and} \quad \vec{X} \sqsubseteq \vec{Y}$$

sequential  $\implies$  continuous  $\implies$  monotonic**1.4 Determinism**

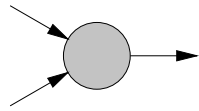
- $S^p$  with  $\sqsubseteq$  forms a complete partial order.
- Fix-point equations  $\vec{X} = \vec{F}(\vec{X})$  have a unique minimal solution when  $\vec{F}$  is continuous.
- Solution to fix-point equations corresponds to histories of channels.
- Histories will be the same for any correct implementation.



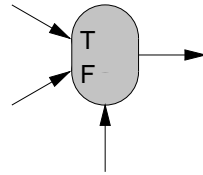
## 2 Dataflow Process Networks

### 2.1 Firing Rules

$$f : S^p \longrightarrow S^q \quad \mathcal{R} = \{\vec{R}_1, \vec{R}_2, \dots, \vec{R}_N\}$$



$$\vec{R} = \{[*], [*]\}$$



$$\vec{R}_1 = \{[T], [*], \perp\}$$

$$\vec{R}_2 = \{[F], \perp, [*]\}$$

## 2.2 Higher Order Functions

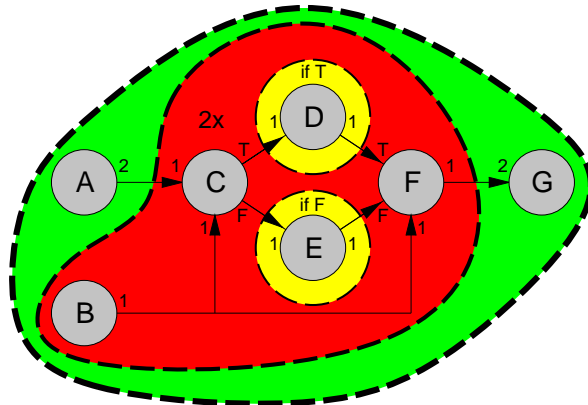
### 2.2.1 $\bar{F} = \text{map}(f)$

$$\text{map}(f)(\vec{R} : \vec{X}) = f(\vec{R}) : \text{map}(f)(\vec{X}) \quad \vec{R} \in \mathcal{R}_f$$

$$\text{map}(f)(\vec{Y}) = \perp \quad \nexists \vec{R} \in \mathcal{R}_f \quad \vec{R} \sqsubseteq \vec{Y}$$

- $f$  sequential  $\implies$   $\bar{F}$  sequential
- $f$  continuous  $\not\implies$   $\bar{F}$  continuous

Sequential firing functions produce determinate process networks.



**Loop:** (conditionally) repeat an actor to match rates with neighbor

**Merge:** combine neighboring actors with same rate

### 2.2.2 $g = \text{loop}(f, N)$

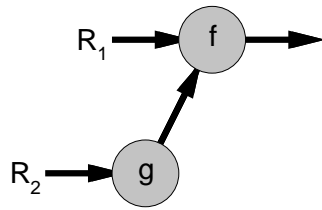
$$\text{loop}(f, N)(\vec{R} : \vec{X}) = f(\vec{R}) : \text{loop}(f, N - 1)(\vec{X}) \quad \vec{R} \in \mathcal{R}_f$$

$$\text{loop}(f, N)(\vec{Y}) = \perp \quad \nexists \vec{R} \in \mathcal{R}_f \quad \vec{R} \sqsubseteq \vec{Y}$$

$$= \perp \quad N = 0$$

What are the firing rules of  $g = \text{loop}(f, N)$  ?

$$\vec{R}_g = \vec{R}_f : \vec{R}_f : \dots \vec{R}_f$$

**2.2.3**  $h = \text{merge}(f, g)$ 

$$\text{merge}(f, g)(\{R_1, R_2\}) = f(\{R_1, g(R_2)\})$$

What are the firing rules of  $h = \text{merge}(f, g)$  ?